AGILE: Lightweight and Efficient Asynchronous GPU-SSD Integration

Zhuoping Yang*, Jinming Zhuang*, Xingzhen Chen*, Alex K. Jones†, and Peipei Zhou*

Brown University*; Syracuse University†;

zhuoping_yang@brown.edu peipei_zhou@brown.edu AGILE is open source!

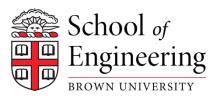


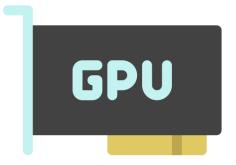
https://peipeizhou-eecs.github.io/

https://github.com/arc-research-lab/AGILE









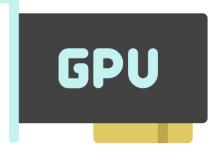
GPGPU: The engine behind modern applications.





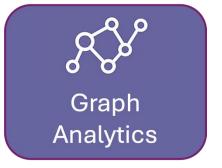








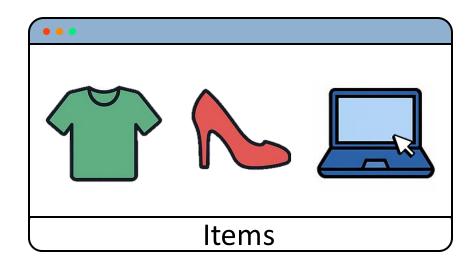
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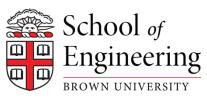


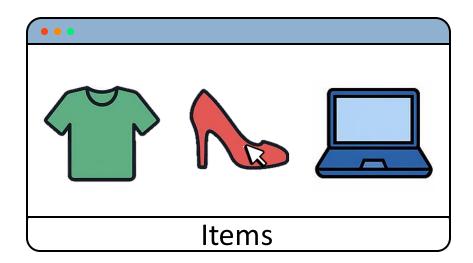




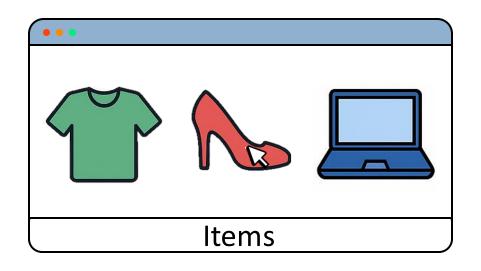


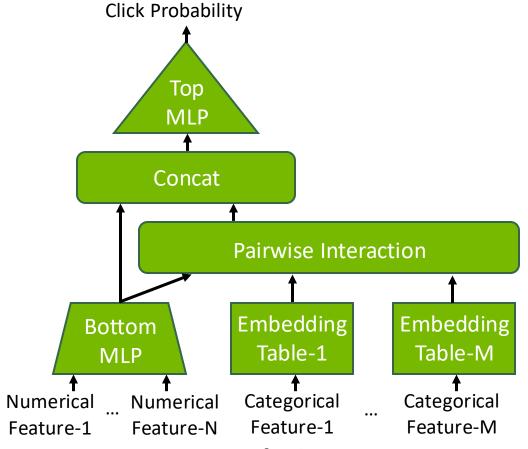






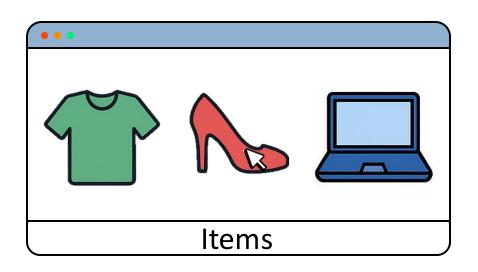


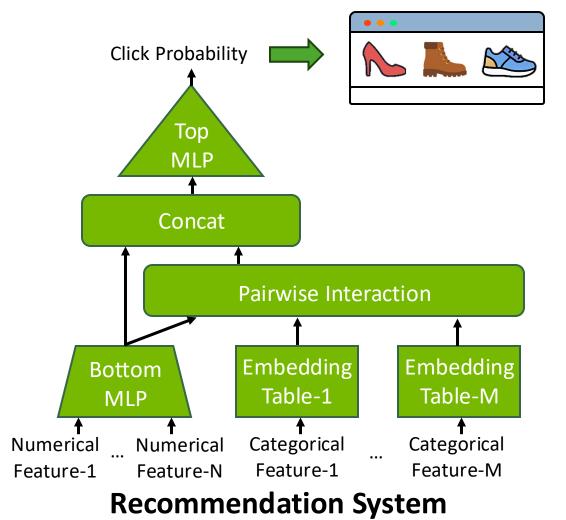


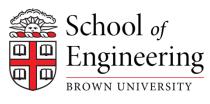


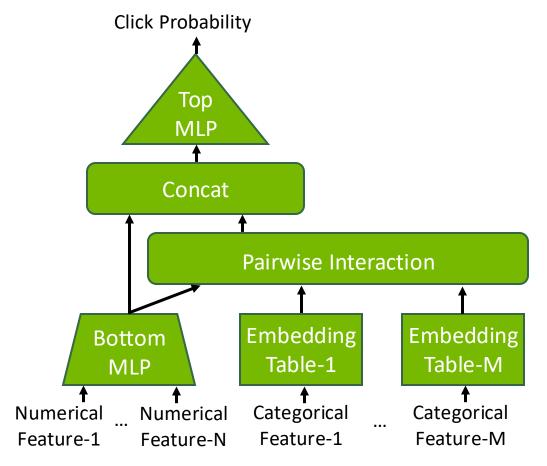
Recommendation System





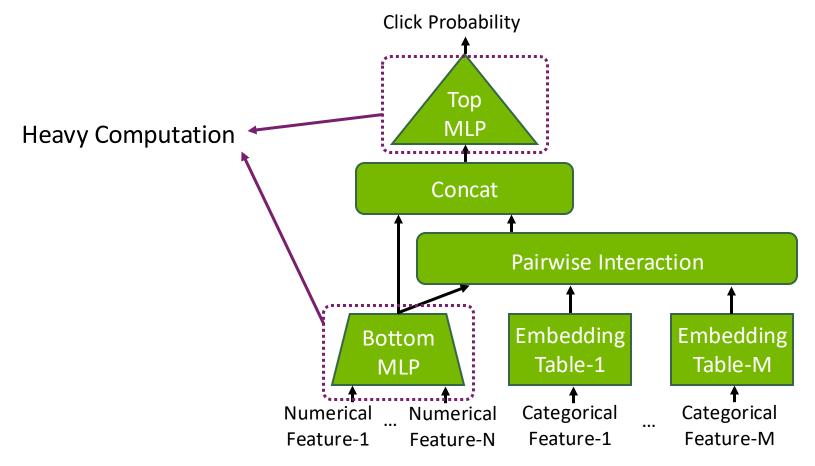






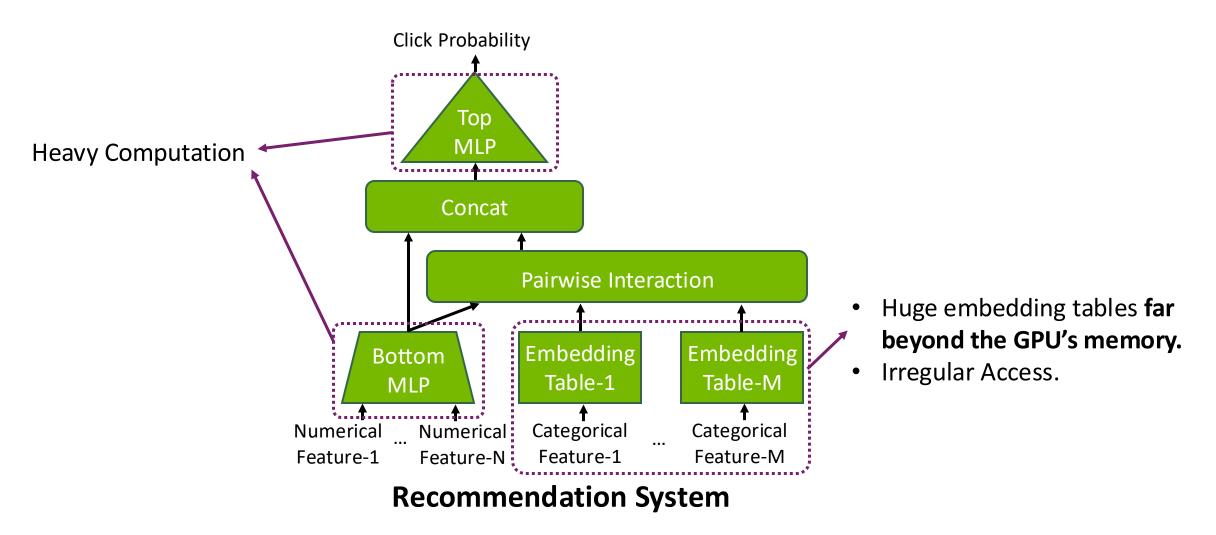
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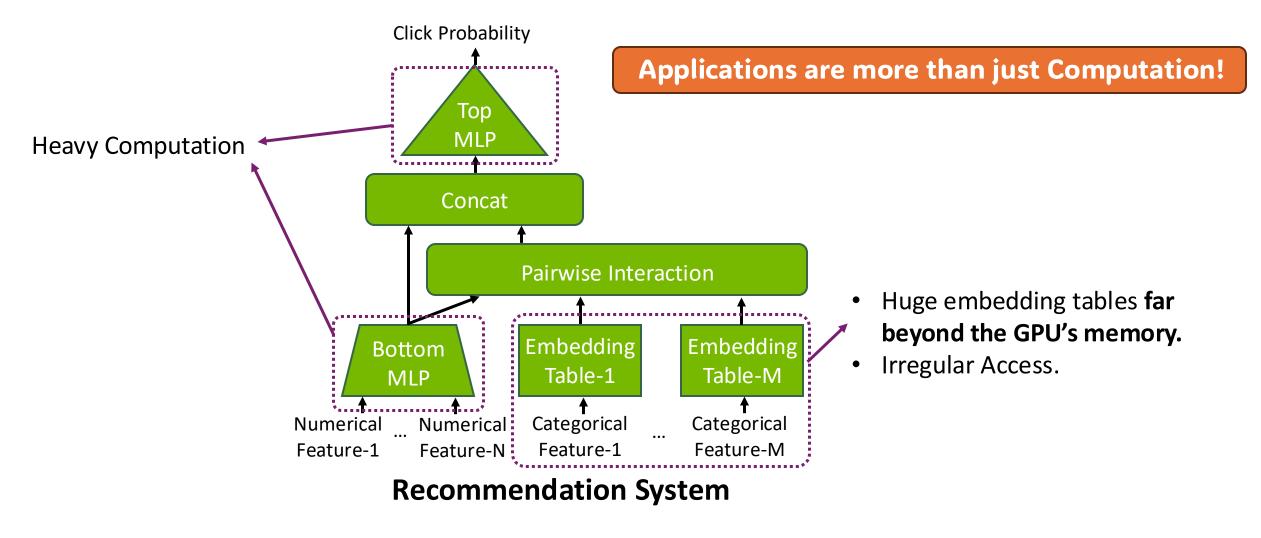


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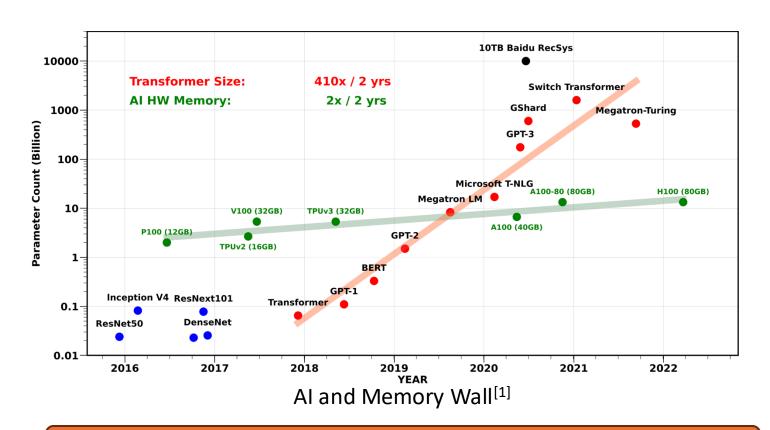




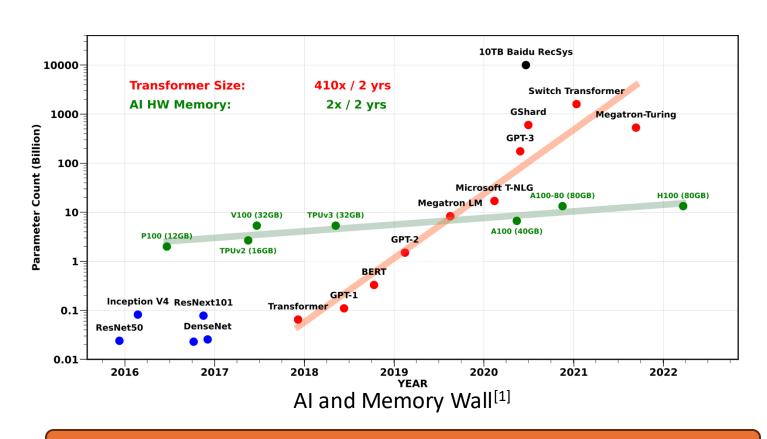


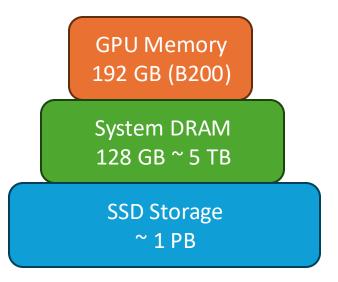






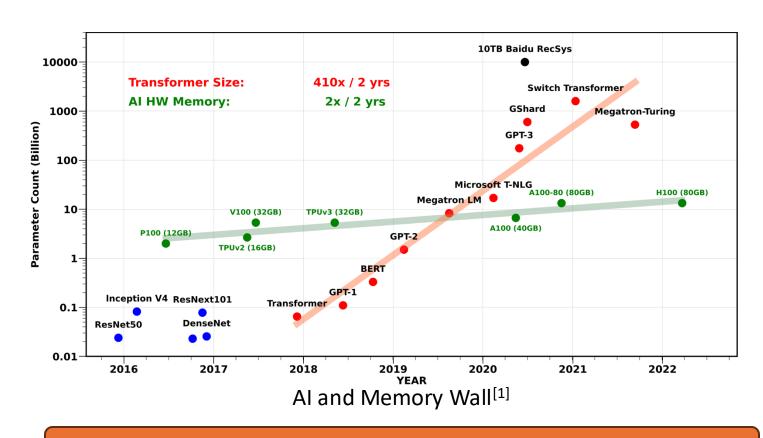


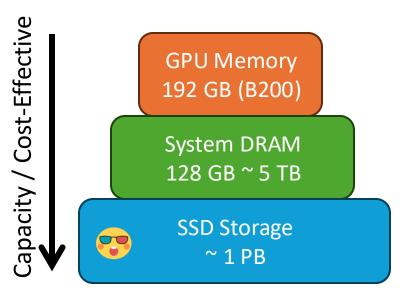




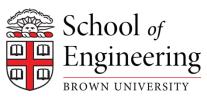
Hierarchical memory in modern computing systems

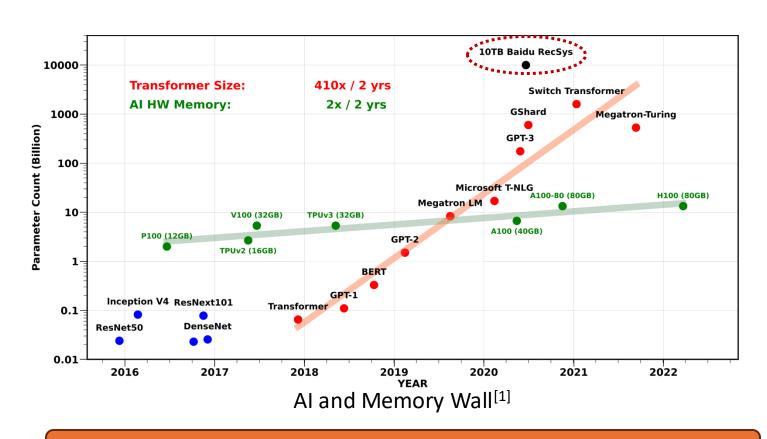


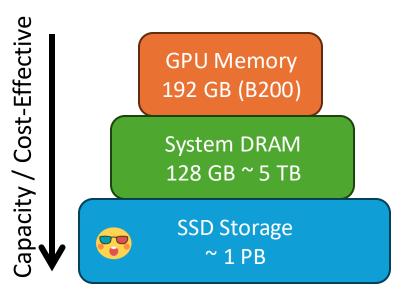




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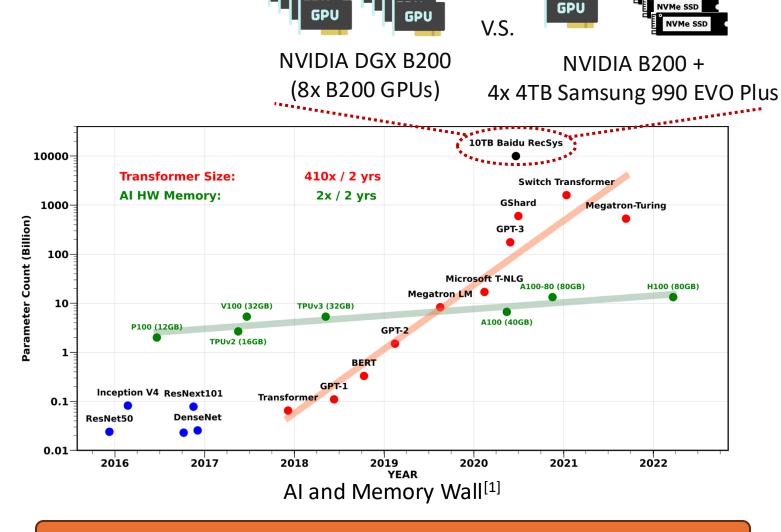




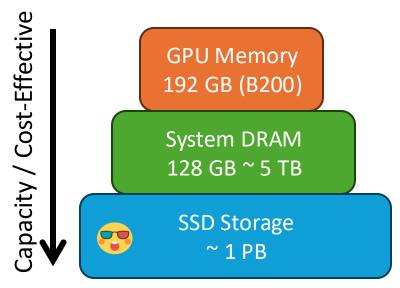


Hierarchical memory in modern computing systems



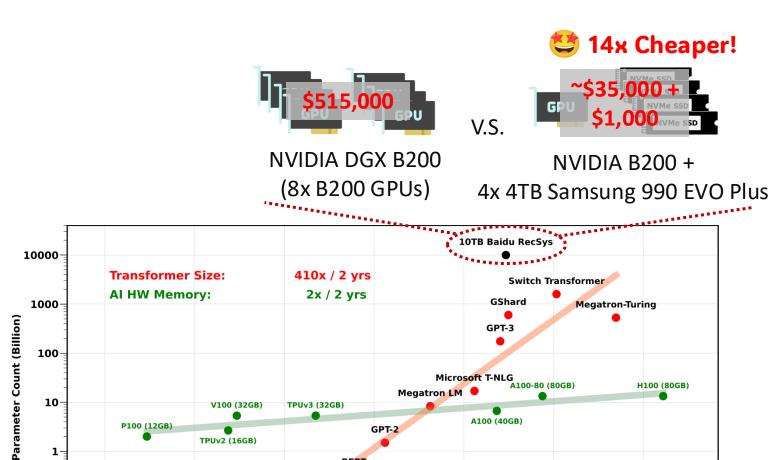


IVMe SSD



Hierarchical memory in modern computing systems

GPUs are increasingly constrained by the memory wall



Microsoft T-NLG

2020

A100 (40GB)

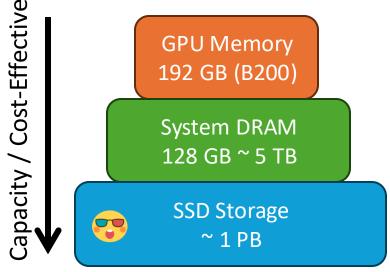
2021

Megatron LM

H100 (80GB)

2022





Hierarchical memory in modern computing systems

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2019 YEAR

Al and Memory Wall^[1]

GPT-2

TPUv3 (32GB)

Transformer

2018

V100 (32GB)

TPUv2 (16GB)

P100 (12GB)

Inception V4 ResNext101

DenseNet

2017

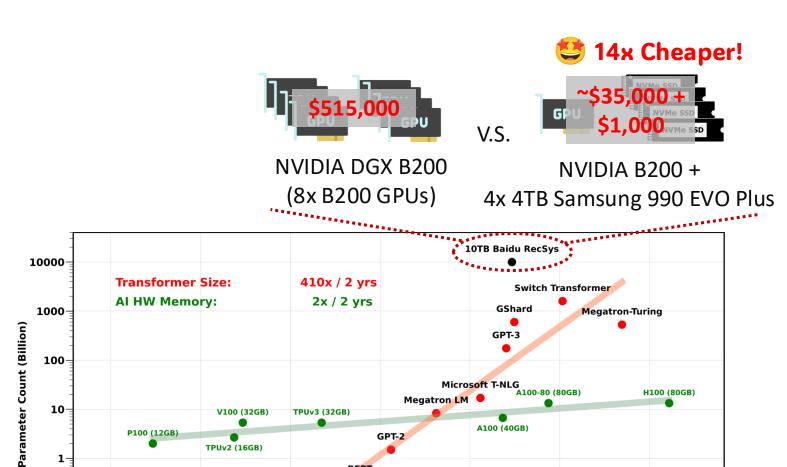
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0.1-

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ResNet50

2016



Microsoft T-NLG

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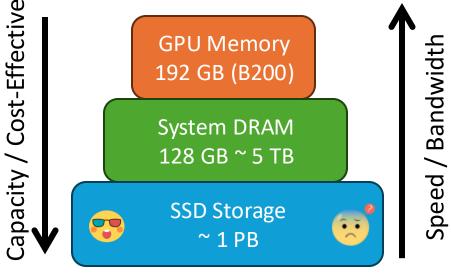
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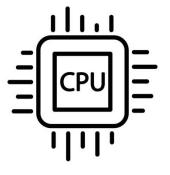
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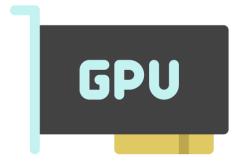
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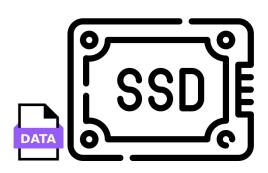
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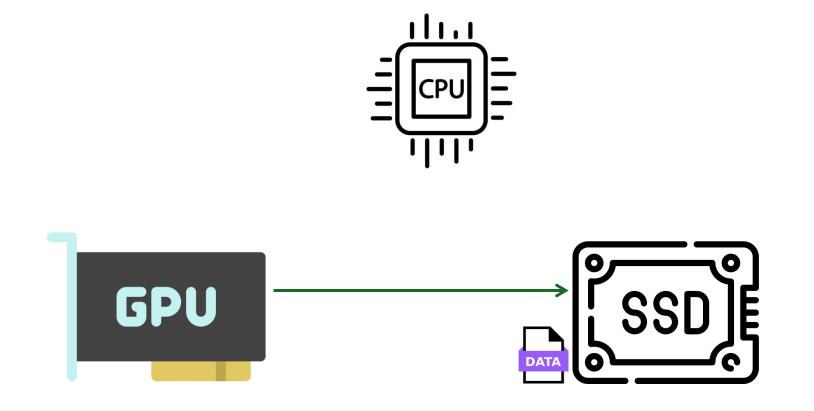




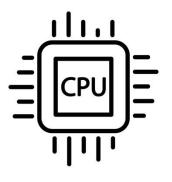


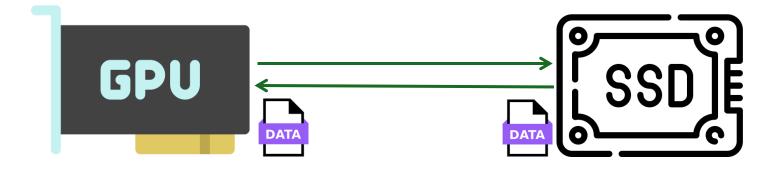








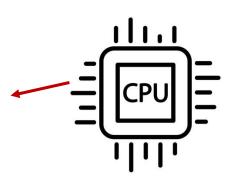






CPU is bypassed completely in both the control plane and the data plane.

No extra copies or synchronization overheads

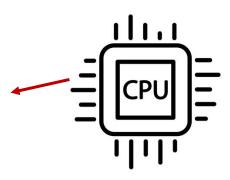


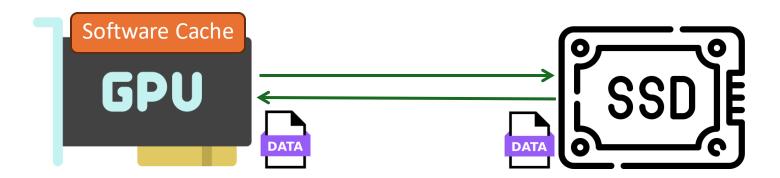




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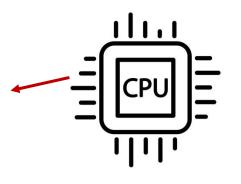






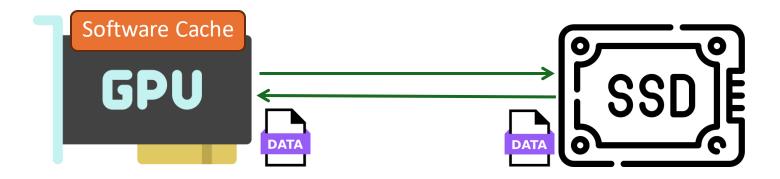
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No extra copies or synchronization overheads





Can we further improve the GPU-centric storage access model?





```
1 def kernel_block_access
2    a = read_block(..)
3    b = read_block(..)
4    compute(a, b)
5    ...
```



- Return after the slow transfer is finished.
- GPU thread must wait for the slow transfer.



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```

Asynchronous I/O Model



```
1 def kernel_block_access
2          a = read_block(..)
3          b = read_block(..);
4          compute(a, b)
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```

Synchronous I/O Model (BaM)

- Return after the slow transfer is finished.
- GPU thread must wait for the slow transfer.

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1 def kernel_async_access
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Asynchronous I/O Model

Return quickly after the request is issued.



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Asynchronous I/O Model

- Return quickly after the request is issued.
- Switch to other tasks during the slow transfer.



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Asynchronous I/O Model

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Async I/O enables overlapping the slow transfer with other tasks.

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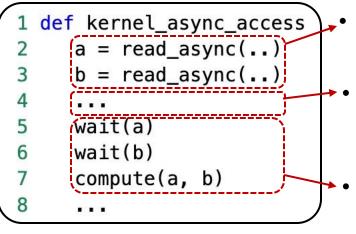


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How can we support an async GPU-centric storage access model efficiently?

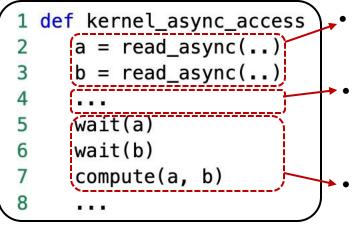


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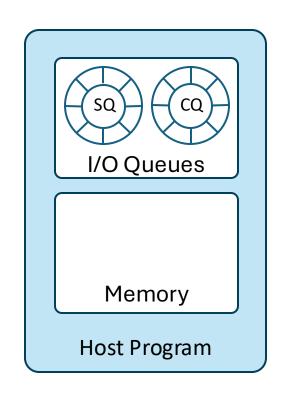
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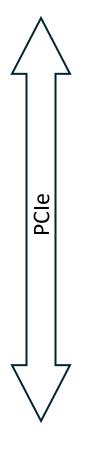
Use AGILE! (this work)

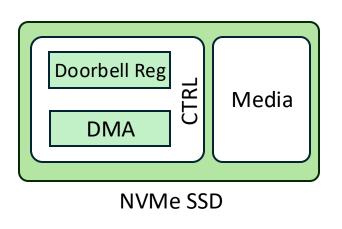


Background of NVMe Protocol



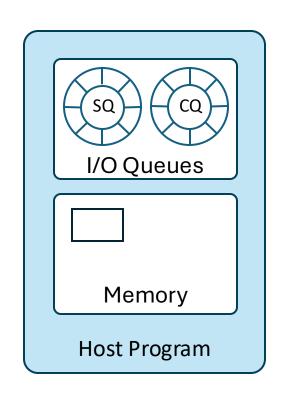


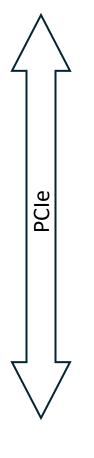


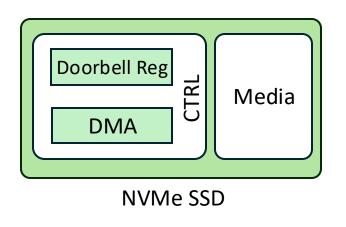


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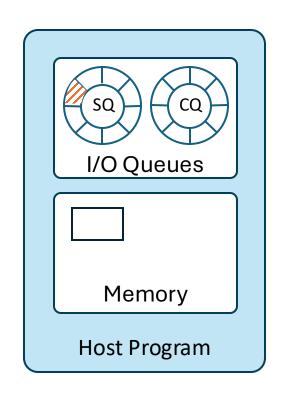


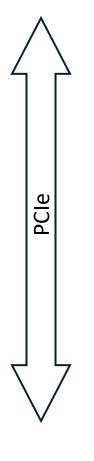


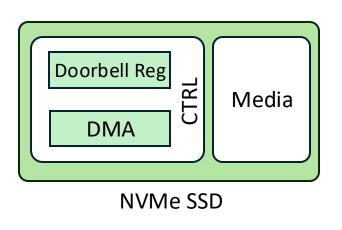


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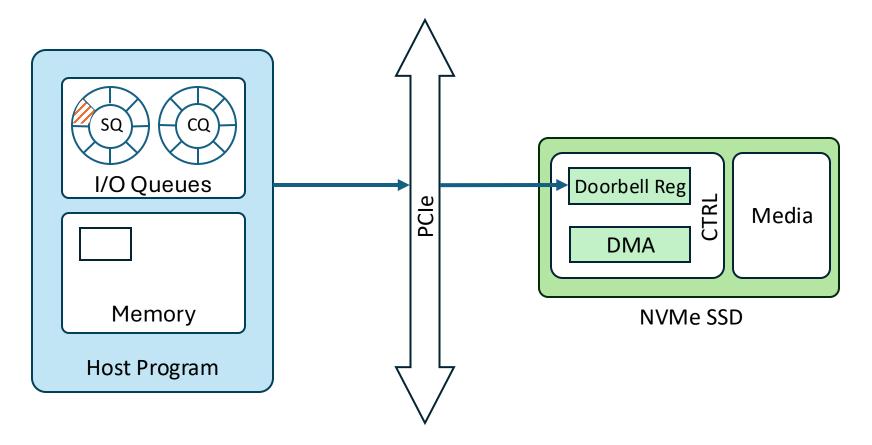




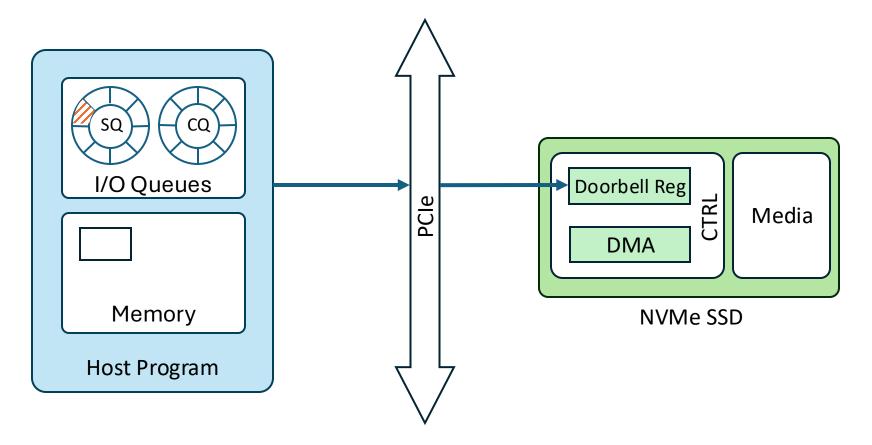




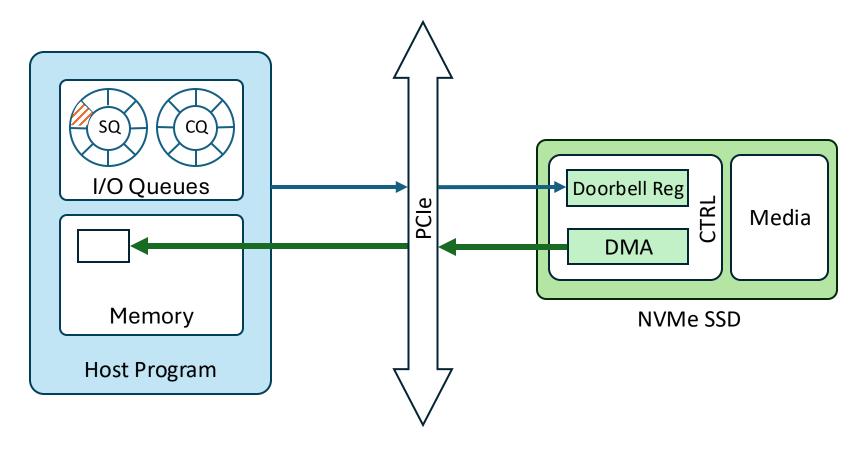




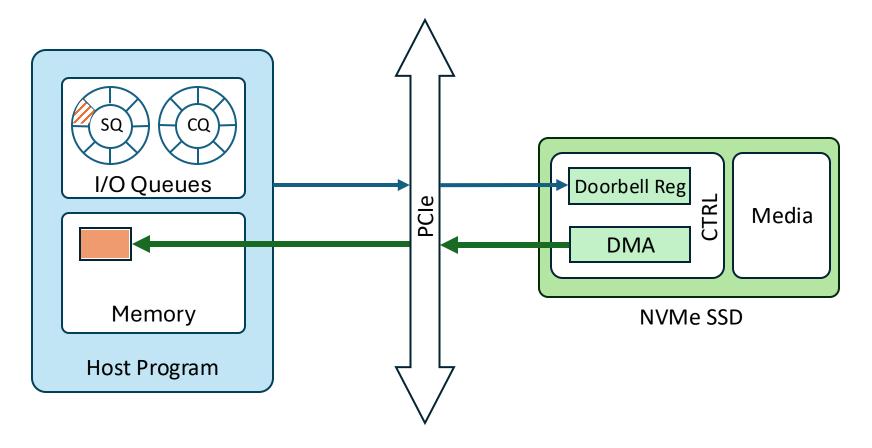




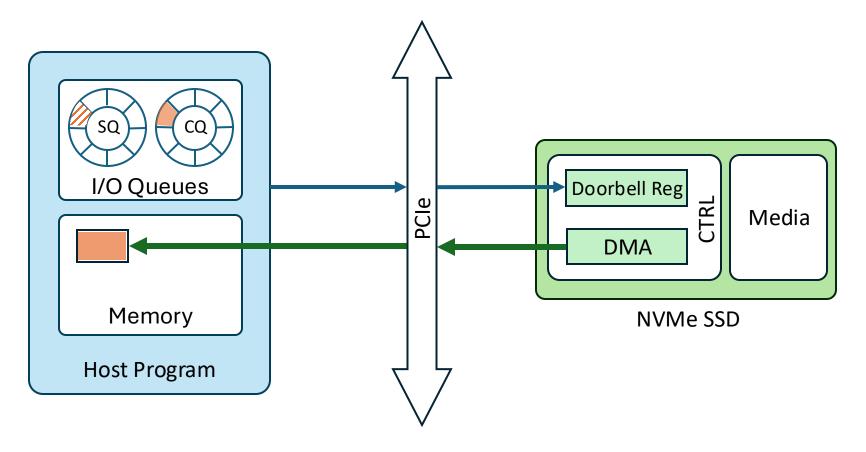




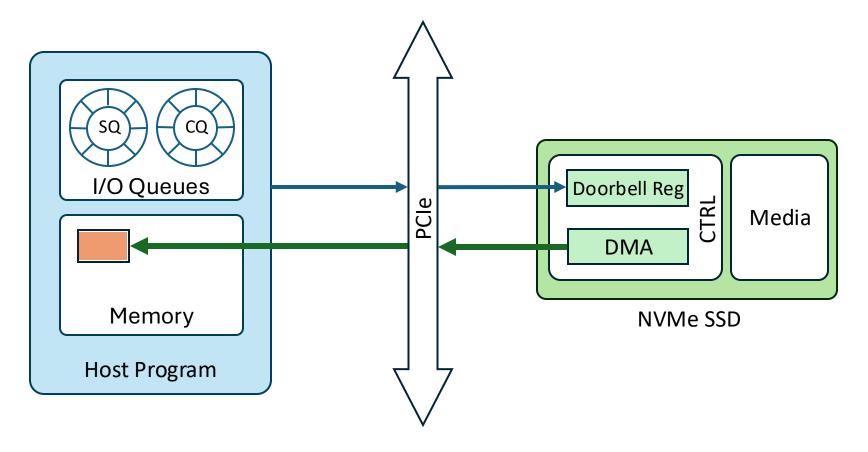




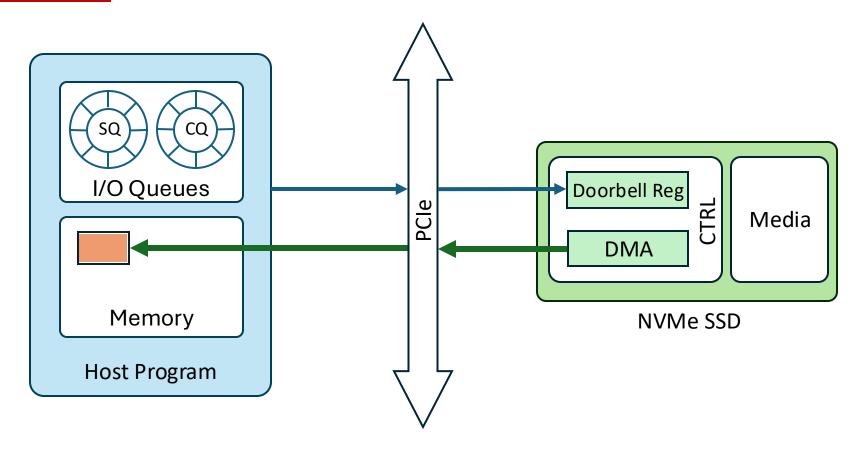






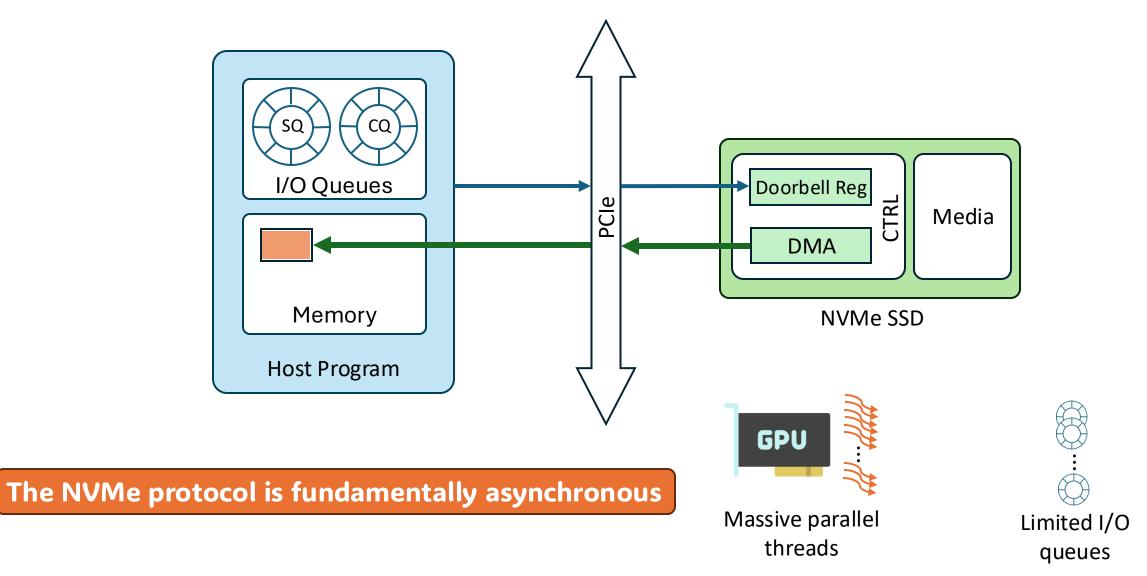




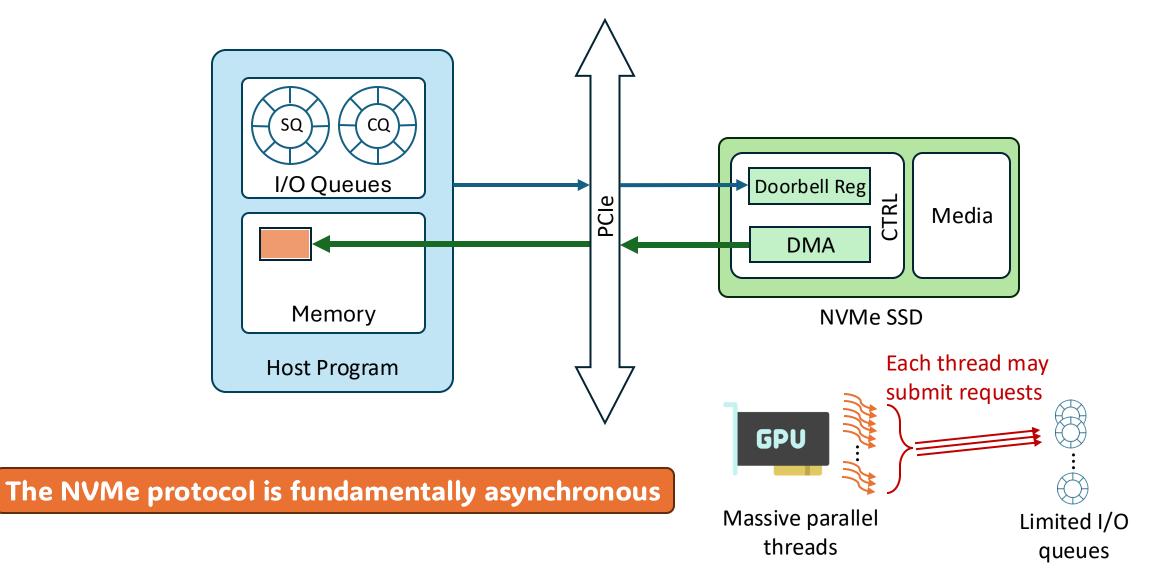


The NVMe protocol is fundamentally asynchronous









Deadlock Risks in Async GPU-Centric NVMe I/O Engineering Engineering



Async GPU-centric NVMe I/O can easily lead to a deadlock.



Async GPU-centric NVMe I/O can easily lead to a deadlock.

```
1 def kernel_async_access
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Async GPU-centric NVMe I/O can easily lead to a deadlock.

```
Thread-1
Thread-2

1 def kernel_async_access
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8    ...
```



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Async GPU-centric NVMe I/O can easily lead to a deadlock.

```
Thread-1

I def kernel_async_access

a = read_async(...)

b = read_async(...)

wait(a)

wait(b)

compute(a, b)

mathread-2

Thread-2

Thread-2

Thread-2

Checking available entries

checking available entries
```



Async GPU-centric NVMe I/O can easily lead to a deadlock.

```
Thread-1

I def kernel_async_access

a = read_async(..)

b = read_async(..)

wait(a)

Not reachable!

x release the SQ entries

wait(b)

compute(a, b)

...
```



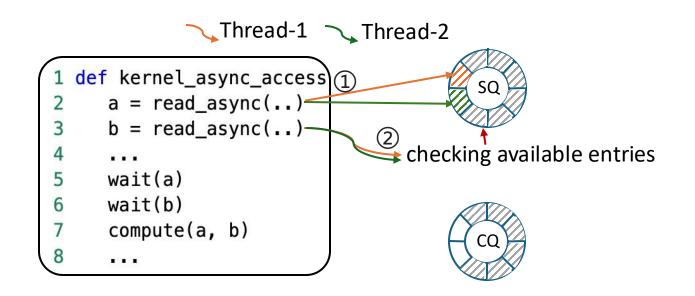
Async GPU-centric NVMe I/O can easily lead to a deadlock.

> A deadlock example in GPU-centric NVMe read:

The root cause of this deadlock is allowing user threads to **hold multiple** locks that can block other user threads. (I/O queues, software cache lines)



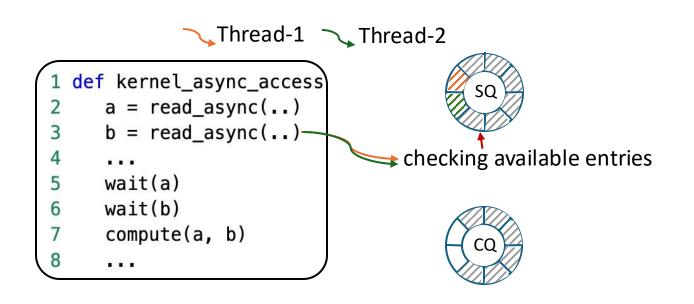
To avoid deadlock from asynchronous NVMe I/O:





To avoid deadlock from asynchronous NVMe I/O:

> A warp-centric AGILE polling service running in the background

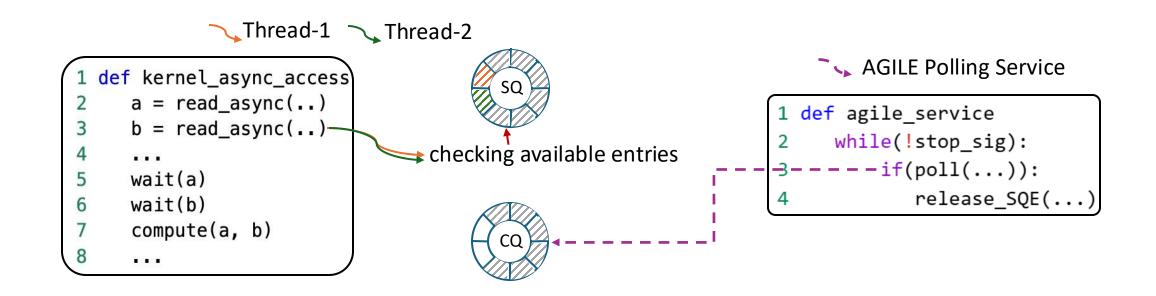


AGILE Polling Service

```
1 def agile_service
2 while(!stop_sig):
3     if(poll(...)):
4     release_SQE(...)
```

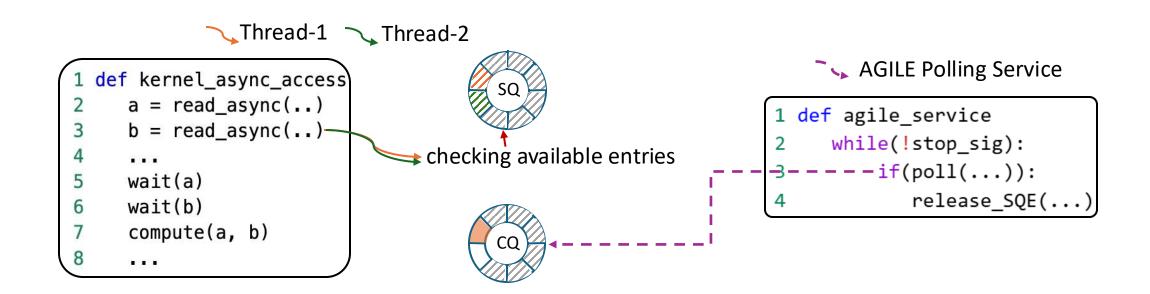


To avoid deadlock from asynchronous NVMe I/O:



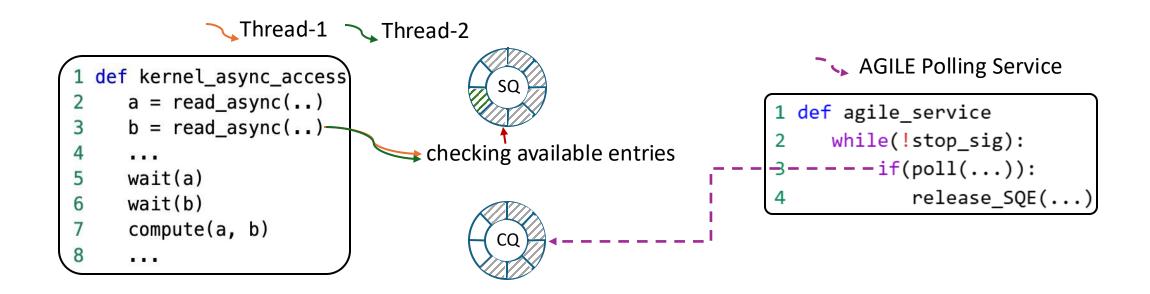


To avoid deadlock from asynchronous NVMe I/O:



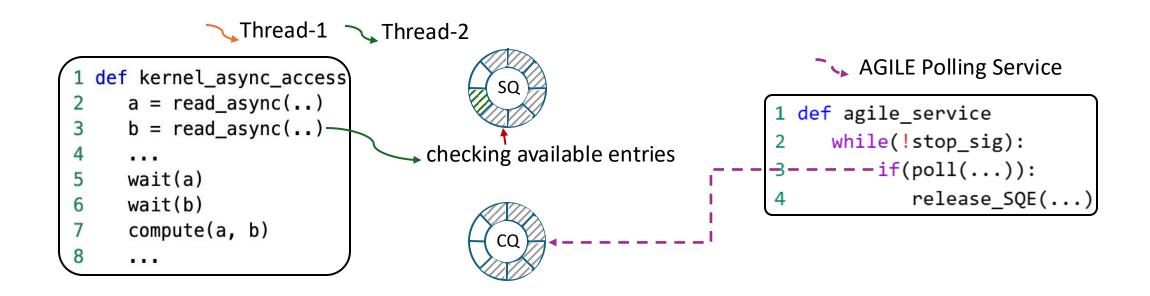


To avoid deadlock from asynchronous NVMe I/O:



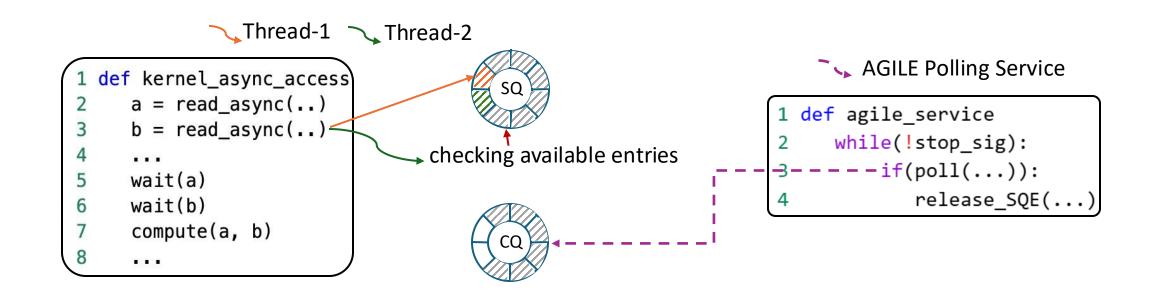


To avoid deadlock from asynchronous NVMe I/O:



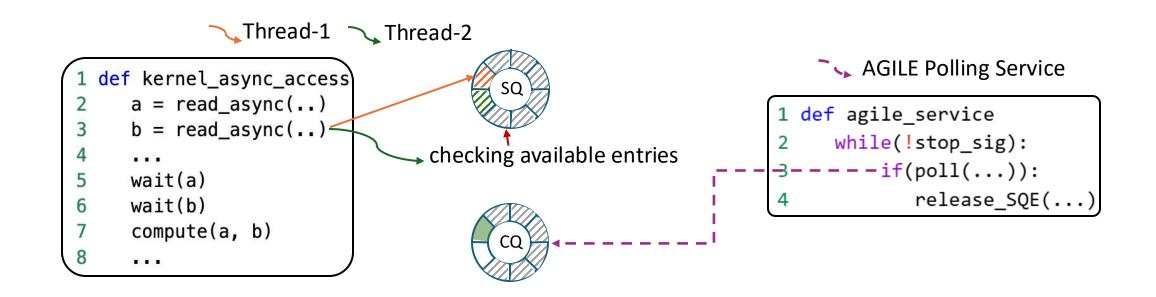


To avoid deadlock from asynchronous NVMe I/O:



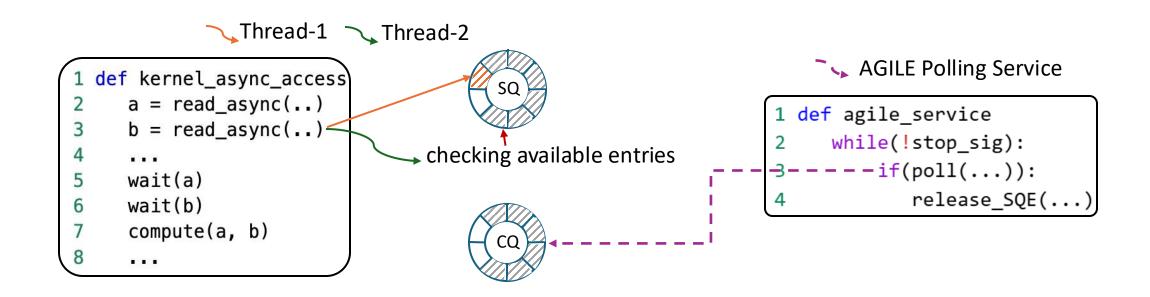


To avoid deadlock from asynchronous NVMe I/O:



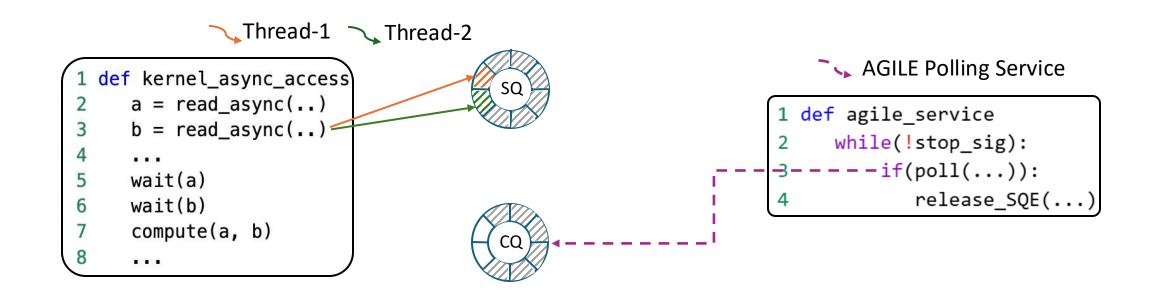


To avoid deadlock from asynchronous NVMe I/O:



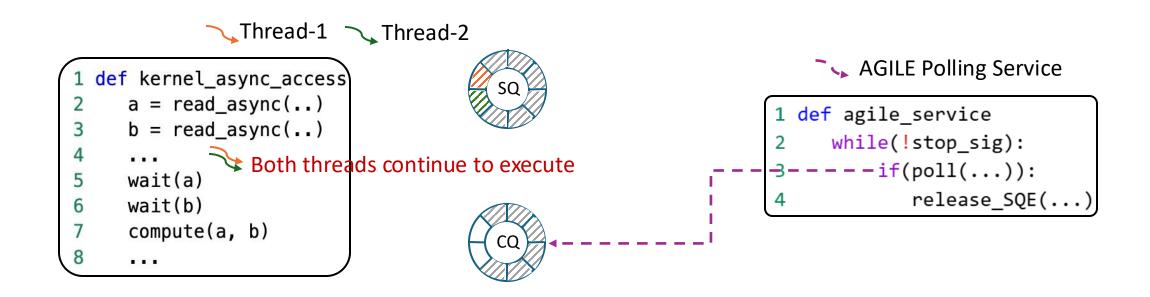


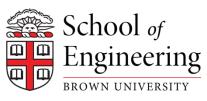
To avoid deadlock from asynchronous NVMe I/O:





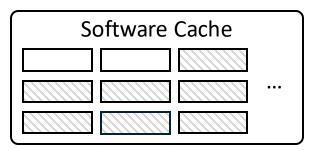
To avoid deadlock from asynchronous NVMe I/O:





To eliminate deadlock from the software cache:

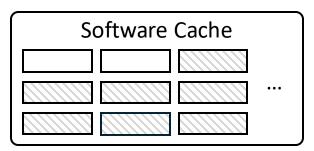
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

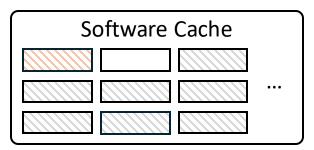
```
1 def kernel_async_access
2 → a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

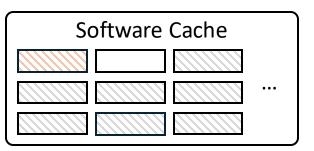
```
1 def kernel_async_access
2 → a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

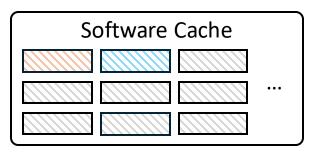
```
1 def kernel_async_access
2    a = read_async(..)
3 → b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

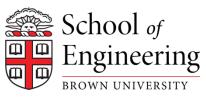




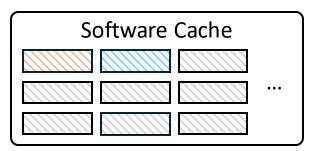
To eliminate deadlock from the software cache:

```
1 def kernel_async_access
2    a = read_async(..)
3 → b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```



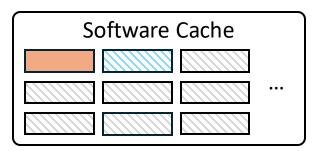


To eliminate deadlock from the software cache:





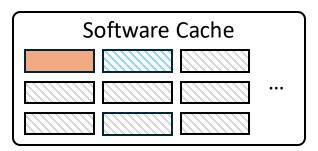
To eliminate deadlock from the software cache:





To eliminate deadlock from the software cache:

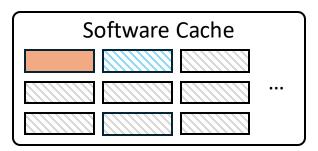
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5 → wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

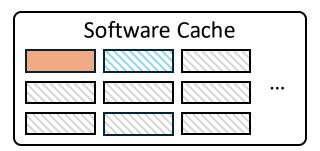
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5 → wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

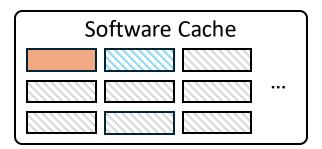
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6 → wait(b)
7    compute(a, b)
8    ...
```

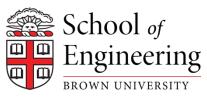




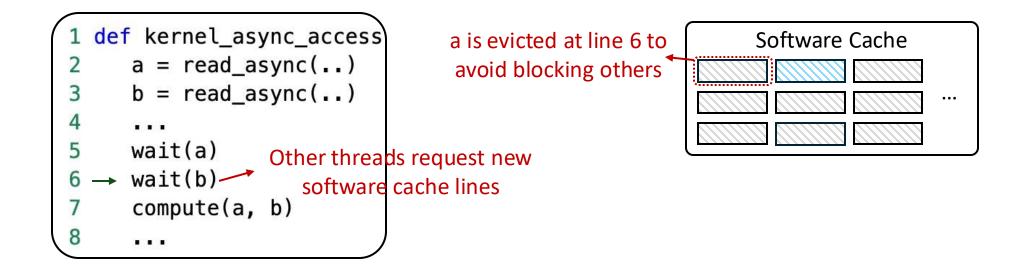
To eliminate deadlock from the software cache:

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a) Other threads request new
6 → wait(b) software cache lines
7    compute(a, b)
8    ...
```





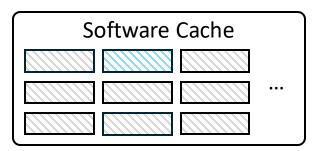
To eliminate deadlock from the software cache:





To eliminate deadlock from the software cache:

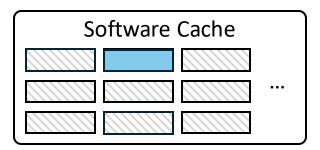
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6 → wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

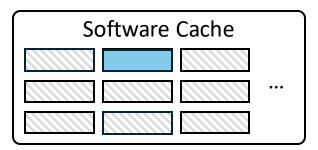
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6 → wait(b)
7    compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

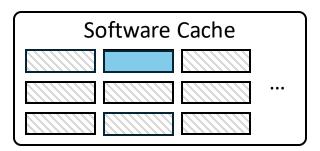
```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7 → compute(a, b)
8    ...
```





To eliminate deadlock from the software cache:

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7 → compute(a, b)
8    ...
Unavailable again
```





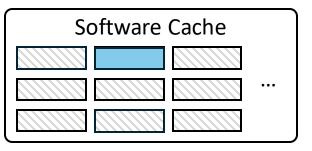
To eliminate deadlock from the software cache:

AGILE does not allow user threads to avoid cache line eviction.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7 → compute(a, b)
8    ...
```

Unavailable again

Use an extra synchronous read when accessing 'a'





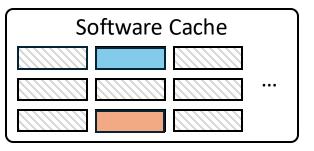
To eliminate deadlock from the software cache:

AGILE does not allow user threads to avoid cache line eviction.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7 → compute(a, b)
8    ...
```

Unavailable again

Use an extra synchronous read when accessing 'a'





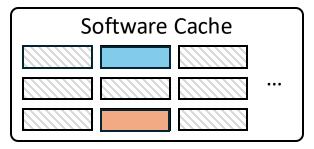
To eliminate deadlock from the software cache:

- AGILE does not allow user threads to avoid cache line eviction.
- ➤ Avoid Deadlocks at the cost of additional I/Os.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7 → compute(a, b)
8    ...
```

Unavailable again

Use an extra synchronous read when accessing 'a'





By default, all accesses are proxied by AGILE software cache.

• Requested data may be unavailable again to eliminate deadlocks.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

Access via AGILE software cache (maybe require additional reads)



By default, all accesses are proxied by AGILE software cache.

- Requested data may be unavailable again to eliminate deadlocks.
- To address this problem, AGILE allows user-managed buffers.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

Access via AGILE software cache (maybe require additional reads)

```
1 def kernel_async_access( \
    a_user_buf, b_user_buf):
2    read_async(a_user_buf)
3    read_async(b_user_buf)
4    ...
5    a_user_buf.wait()
6    b_user_buf.wait()
7    compute(a_user_buf, b_user_buf)
8    ...
```



By default, all accesses are proxied by AGILE software cache.

- Requested data may be unavailable again to eliminate deadlocks.
- To address this problem, AGILE allows user-managed buffers.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

Access via AGILE software cache (maybe require additional reads)

User-managed buffers



By default, all accesses are proxied by AGILE software cache.

- Requested data may be unavailable again to eliminate deadlocks.
- To address this problem, AGILE allows user-managed buffers.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

Access via AGILE software cache (maybe require additional reads)



By default, all accesses are proxied by AGILE software cache.

- Requested data may be unavailable again to eliminate deadlocks.
- To address this problem, AGILE allows user-managed buffers.

```
1 def kernel_async_access
2    a = read_async(..)
3    b = read_async(..)
4    ...
5    wait(a)
6    wait(b)
7    compute(a, b)
8    ...
```

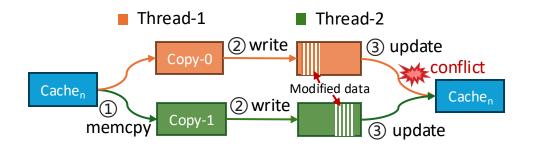
Access via AGILE software cache (maybe require additional reads)



When multiple threads request the same data, data conflicts may occur.

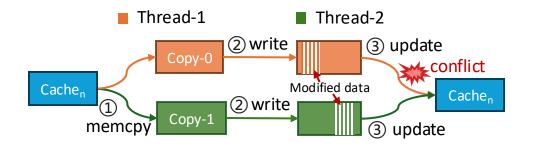


When multiple threads request the same data, data conflicts may occur.





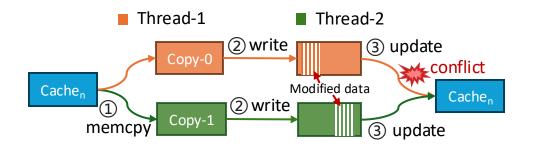
When multiple threads request the same data, data conflicts may occur.



AGILE provides a compile-time optional mechanism (share-table) to let user threads access the same user-managed buffer.



When multiple threads request the same data, data conflicts may occur.



AGILE provides a compile-time optional mechanism (share-table) to let user threads access the same user-managed buffer.

When the share-table is enabled at compile time:

- user-managed buffer (L1; managed by user; registered to share-table)
- Software cache (L2; managed by AGILE)
- SSDs (L3; managed by AGILE)



```
class GPUCache:public GPUCacheBase < GPUCache > { . . . };
#define AGILE_CTRL AgileCtrl<GPUCache, ShareTable>
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
  AgileLockChain chain;
  // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
  // Method-2: AGILE async_issue
  AgileBufPtr buf(data + tid * ctrl->line_size);
  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
  buf.wait();
  ctrl->asyncWrite(dev_idx, blk_idx, buf, chain);
  // Method-3: AGILE array-like synchronous API
  auto agileArr = ctrl->getArrayWrap<int>(chain);
  int val = agileArr[dev_idx][idx];
```

```
int main(int argc, char** argv){
    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.initNvme():
    // Initialize AGILE controller
    host.initializeAgile(...);
    // CUDA kernel parallelism configurations
    host.configKernelParallelism(...);
    host.gueryOccupancy(kernel);
    // Start the lightweight AGILE service
    host.startAgile();
    // Execute the CUDA kernel
    host.runKernel(kernel, args...);
    // Stop AGILE service
    host.stopAgile();
    // Close the opened SSDs
    host.closeNvme();
```



```
class GPUCache:public GPUCacheBase < GPUCache > { . . . };
#define AGILE_CTRL AgileCtrl<GPUCache, ShareTable>
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
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 // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
  // Method-2: AGILE async_issue
  AgileBufPtr buf(data + tid * ctrl->line_size);
  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
  buf.wait();
  ctrl->asyncWrite(dev_idx, blk_idx, buf, chain);
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  int val = agileArr[dev_idx][idx];
```

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    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
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    host.initNvme();
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```



```
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 // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
 // Method-2: AGILE async_issue
  AgileBufPtr buf(data + tid * ctrl->line_size);
  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
  buf.wait();
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```

```
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    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.initNvme();
    // Initialize AGILE controller
    host.initializeAgile(...);
    // CUDA kernel parallelism configurations
    host.configKernelParallelism(...);
    host.gueryOccupancy(kernel);
    // Start the lightweight AGILE service
    host.startAgile();
    // Execute the CUDA kernel
    host.runKernel(kernel, args...);
    // Stop AGILE service
    host.stopAgile();
    // Close the opened SSDs
    host.closeNvme();
```



```
class GPUCache:public GPUCacheBase < GPUCache > { . . . };
#define AGILE_CTRL AgileCtrl<GPUCache, ShareTable>
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
  AgileLockChain chain;
 // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
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  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
  buf.wait();
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```

```
int main(int argc, char** argv){
    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.initNvme();
    // Initialize AGILE controller
    host.initializeAgile(...);
    // CUDA kernel parallelism configurations
    host.configKernelParallelism(...);
    host.gueryOccupancy(kernel);
    // Start the lightweight AGILE service
    host.startAgile();
    // Execute the CUDA kernel
    host.runKernel(kernel, args...);
    // Stop AGILE service
    host.stopAgile();
    // Close the opened SSDs
    host.closeNvme();
```



Customizing software cache policy

```
class GPUCache:public GPUCacheBase < GPUCache > { . . . };
#define AGILE_CTRL AgileCtrl < GPUCache, ShareTable >
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
  AgileLockChain chain;
 // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
  // Method-2: AGILE async_issue
  AgileBufPtr buf(data + tid * ctrl->line_size);
  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
  buf.wait();
  ctrl->asyncWrite(dev_idx, blk_idx, buf, chain);
 // Method-3: AGILE array-like synchronous API
  auto agileArr = ctrl->getArrayWrap<int>(chain);
  int val = agileArr[dev_idx][idx];
```

```
int main(int argc, char** argv){
    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.initNvme();
   // Initialize AGILE controller
    host.initializeAgile(...);
    // CUDA kernel parallelism configurations
    host.configKernelParallelism(...);
    host.gueryOccupancy(kernel);
    // Start the lightweight AGILE service
    host.startAgile();
    // Execute the CUDA kernel
    host.runKernel(kernel, args...);
    // Stop AGILE service
    host.stopAgile();
   // Close the opened SSDs
    host.closeNvme();
```



Customizing software cache policy

```
class GPUCache:public GPUCacheBase < GPUCache > { . . . }
#define AGILE_CTRL AgileCtrl < GPUCache, ShareTable >
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
 AgileLockChain chain; Debug option for
                           detecting deadlock
 // Method-1: AGILE prefetch
  ctrl->prefetch(dev_idx, blk_idx, chain);
  // Method-2: AGILE async_issue
  AgileBufPtr buf(data + tid * ctrl->line_size);
  ctrl->asyncRead(dev_idx, blk_idx, buf, chain);
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  ctrl->asyncWrite(dev_idx, blk_idx, buf, chain);
 // Method-3: AGILE array-like synchronous API
  auto agileArr = ctrl->getArrayWrap<int>(chain);
  int val = agileArr[dev_idx][idx];
```

```
int main(int argc, char** argv){
    // GPU Configurations
    AGILE_HOST host(...);
    // Policy Configurations
    SHARE_TABLE_IMPL s_table(...);
    GPU_CACHE_IMPL g_cache(...);
    host.setGPUCache(g_cache);
    host.setShareTable(s_table);
    // Add and open target SSDs in the program
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.addNvmeDev("/dev/AGILE-xxx", ...);
    host.initNvme();
    // Initialize AGILE controller
    host.initializeAgile(...);
    // CUDA kernel parallelism configurations
    host.configKernelParallelism(...);
    host.gueryOccupancy(kernel);
    // Start the lightweight AGILE service
    host.startAgile();
    // Execute the CUDA kernel
    host.runKernel(kernel, args...);
    // Stop AGILE service
    host.stopAgile();
    // Close the opened SSDs
    host.closeNvme();
```



Customizing software cache policy

```
class GPUCache:public GPUCacheBase < GPUCache > { . . . };
#define AGILE_CTRL AgileCtrl < GPUCache, ShareTable >
__global__
void kernel(AGILE_CTRL * ctrl, void * data){
                        → Debug option for
 (AgileLockChain chain;)
                           detecting deadlock
 // Method-1: AGILE prefetch
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   // Start the lightweight AGILE service
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Init AGILE & Start AGILE service



Customizing software cache policy

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   host.startAgile();
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                                               Start user kernel
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   // Close the opened SSDs
    host.closeNvme();
```

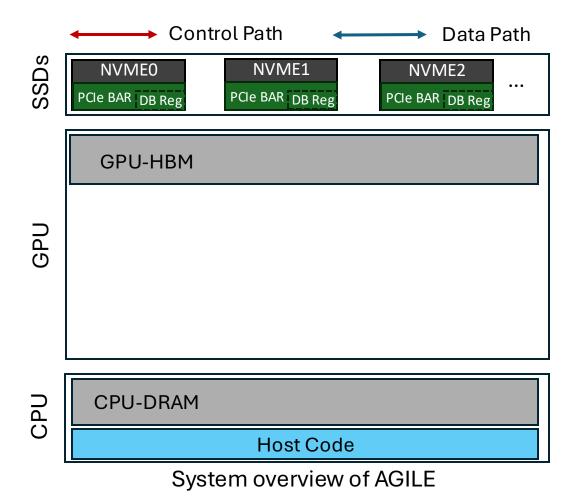


Customizing software cache policy

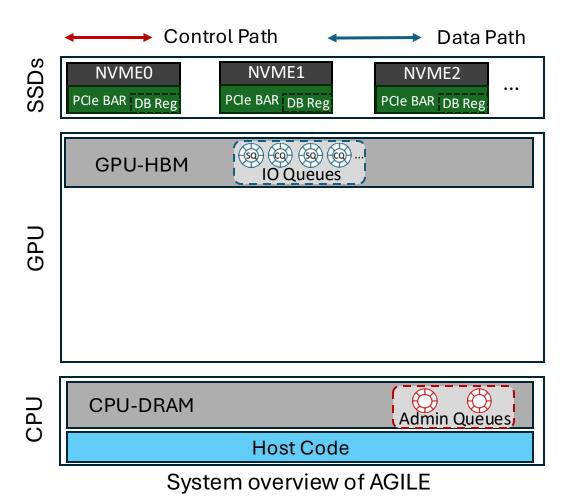
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                                               Start user kernel
   host.runKernel(kernel, args...);
   // Stop AGILE service
   host.stopAgile();
                                               Stop AGILE
   // Close the opened SSDs
                                                service & close
   host.closeNvme();
                                                SSDs
```

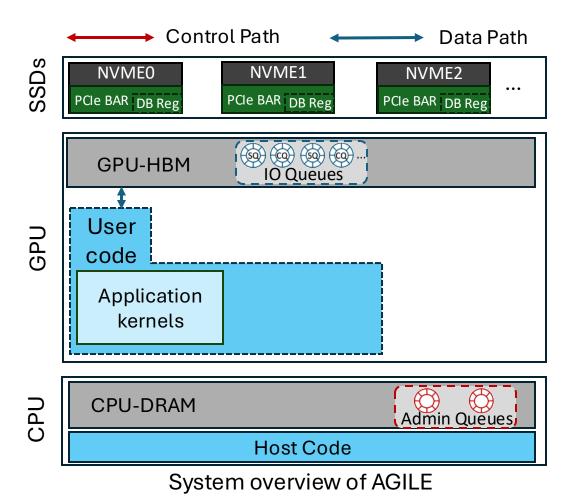


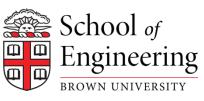






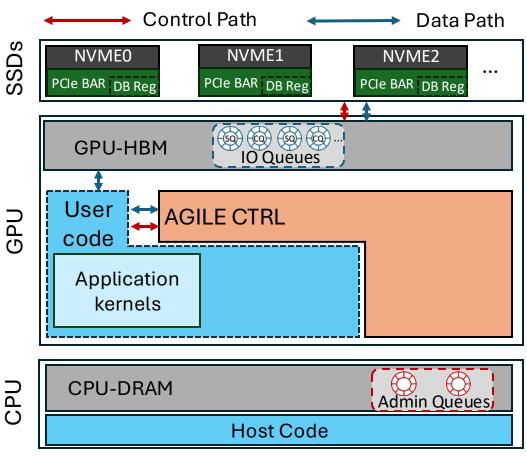






Feature Highlights:

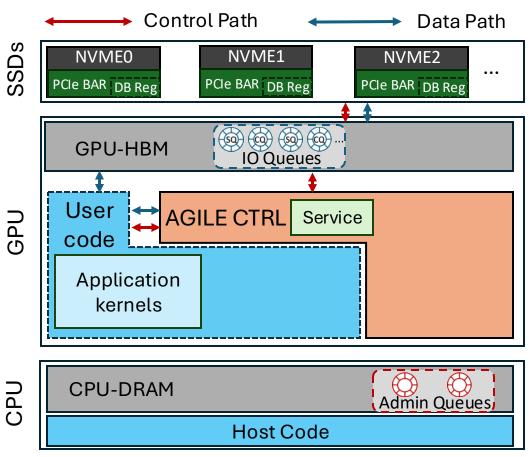
1. AGILE is the first async GPU-centric I/O model, allowing GPU threads to access SSDs asynchronously.



System overview of AGILE

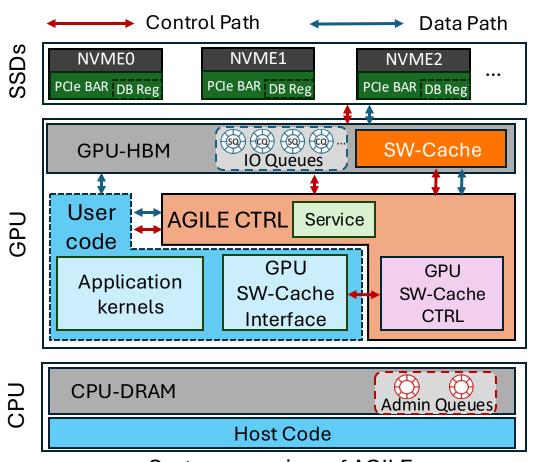


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- 3. AGILE allows users to customize software cache policies.



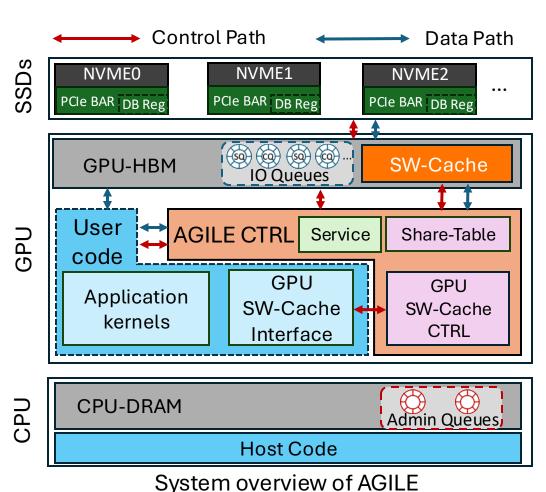
System overview of AGILE

Summary of AGILE

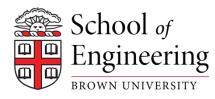


Feature Highlights:

- 1. AGILE is the first async GPU-centric I/O model, allowing GPU threads to access SSDs asynchronously.
- 2. AGILE eliminates the deadlock risks in asynchronous NVMe I/O via AGILE polling service.
- 3. AGILE allows users to customize software cache policies.
- 4. AGILE allows user-maintained buffers to be integrated into the software cache hierarchy.



Experimental Setup



- Dell R750 Server
 - Ubuntu 20.04 (Linux 5.4.0-200-generic)
- Nvidia RTX 5000 Ada GPU (PCle Gen4 x16)
- NVMe SSDs
 - Dell Ent NVMe AGN MU AIC 1.6TB SSD (PCIe Gen4 x4)
 - Two Samsung 990 PRO 1TB SSDs (PCle Gen4 x4)
- Software Cache Policy
 - Clock replacement algorithm^[1] (keep the same with BaM)



1. Compute and communication overlap.

• 1 thread block issues 64 NVMe commands, and uses fetched data for compute.

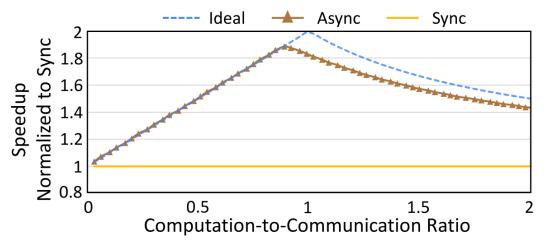


Figure 4: Speedup comparison of asynchronous I/O over synchronous I/O on workloads with different Computation-to-Communication Ratio (CTC).



- 1. Compute and communication overlap.
 - 1 thread block issues 64 NVMe commands, and uses fetched data for compute.
- >AGILE can hide slow communication with computation effectively.

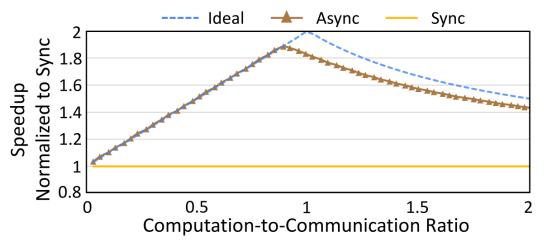


Figure 4: Speedup comparison of asynchronous I/O over synchronous I/O on workloads with different Computation-to-Communication Ratio (CTC).



- 2. Scalability in 4KB random read/write
 - Access different SSDs in an interleaving fashion.

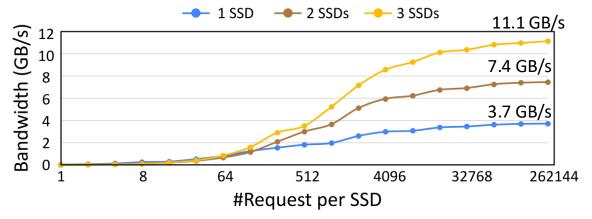


Figure 5: AGILE 4KB random read on multiple SSDs

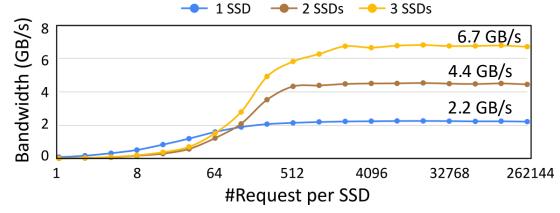


Figure 6: AGILE 4KB random write on multiple SSDs



- 2. Scalability in 4KB random read/write
 - Access different SSDs in an interleaving fashion.
- ➤ AGILE shows good scalability.

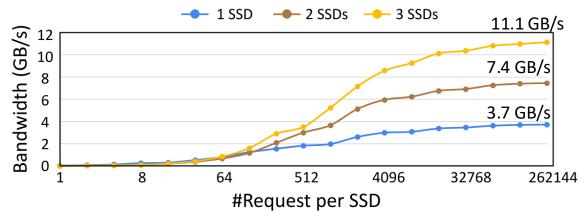


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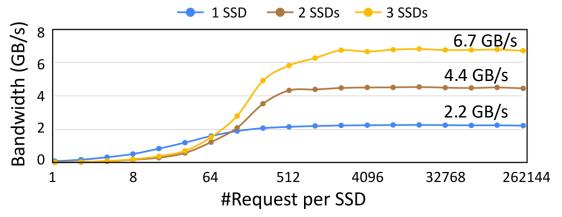
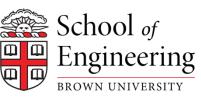


Figure 6: AGILE 4KB random write on multiple SSDs



- 3. Comparison with BaM on DLRM inference MicroBenchmark.
 - The DLRM model is adopted from [1] with Criteo 1TB Click Logs dataset[2].
 - cuBLAS is used for all matrix multiplications.
 - BaM and AGILE are used for fetching data.
 - AGILE is used in both synchronous mode and asynchronous mode



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Default parameters:

- Batch Size: 2048
- #I/O queues: 128
- Software cache size: 2 GB
- Sweep key parameter: Batch Size & the Number of I/O Queues.



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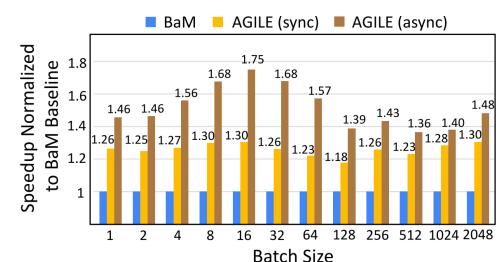
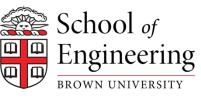


Figure 8: Speedup comparison of AGILE (async and sync modes) and BaM across varying batch sizes in DLRM inference.

Sweep key parameter: Batch Size & the Number of I/O Queues.

[1] Naumov, Maxim, et al. "Deep learning recommendation model for personalization and recommendation systems." arXiv preprint arXiv:1906.00091 (2019).



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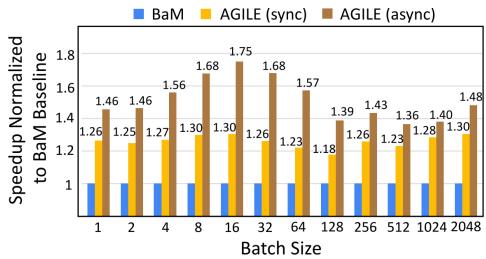


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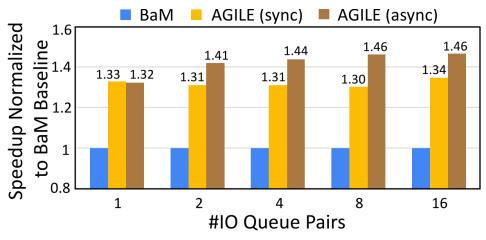


Figure 9: Speedup comparison of AGILE (async and sync modes) and BaM under varying numbers of I/O queue pairs in DLRM inference.

^[1] Naumov, Maxim, et al. "Deep learning recommendation model for personalization and recommendation systems." arXiv preprint arXiv:1906.00091 (2019).



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- Sweep key parameter: Software Cache Size

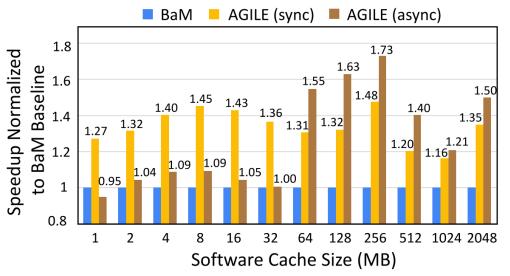


Figure 10: Speedup comparison of AGILE (async and sync modes) and BaM under varying software cache sizes in DLRM inference.

Default parameters:

- Batch Size: 2048
- #I/O queues: 128
- Software cache size: 2 GB

THANK YOU? QUESTIONS?

zhuoping_yang@brown.edu peipei_zhou@brown.edu

AGILE is open source!









